Design Robotics

Developing new ways to use robots for design-led manufacturing





JRMII UNIVERSITY









Development of an automated robotic polishing system for one-of-a-kind production

Barış Balcı PhD Student, QUT

Robots in Manufacturing

Mass

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IMCFC









Custom (One-of-a-kind)



Image credits Tesla Factory, https://en.wikipedia.org/wiki/Tesla_Factory UAP

Polishing Operations

A finishing operation

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Highly skilled operators

UAP

QUT

QUT Design Lab





OROBOTIC

IMCrC

Hand-eye coordination



Robotic Polishing Operations

How can we transfer hand-eye coordination skill to a robot?

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imere





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Vision Hearing Smell Taste Touch

Touch

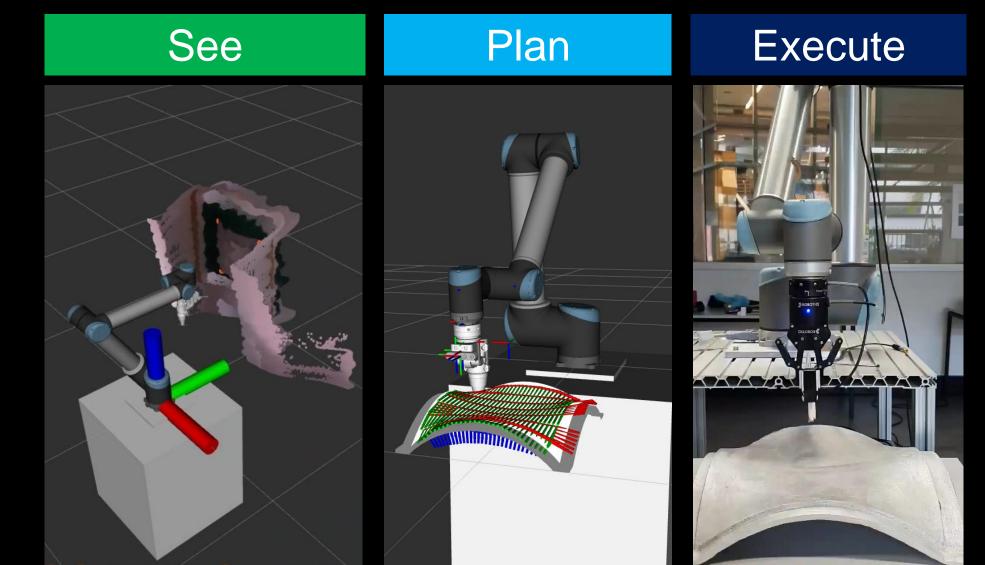
Vision





Image credits RealSense Camera, Intel Robotiq Force Torque Sensor, Universal Robots

Our Approach



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Thanks!

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