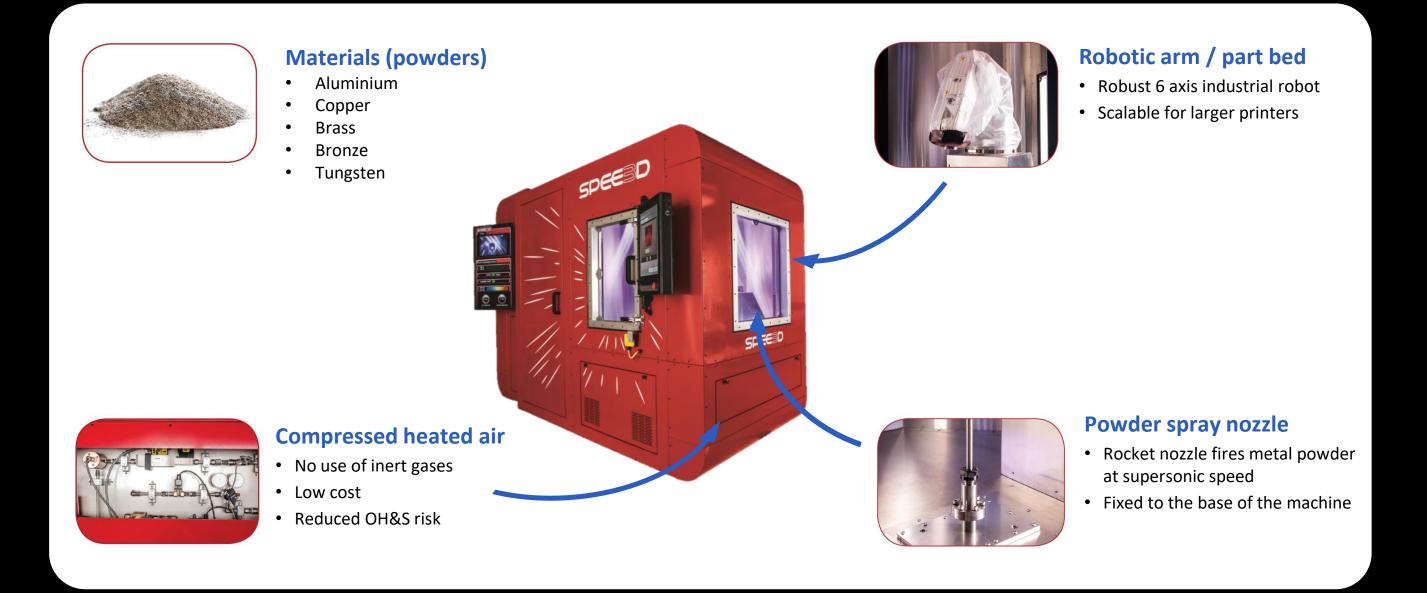
# Machine Vision for High Speed Printing



#### SPEE3D – Australian 3D Printer Manufacturer





### The Future of Manufacturing

#### **Metal Parts**

> Low cost

> On site / on demand parts

> Quality control – 3D Scanning

#### **Industries This Will Impact**

- > Defence (Navy, Airforce, Army)
- > Mining / Oil and Gas
- > Aerospace / Automotive
- > General industry



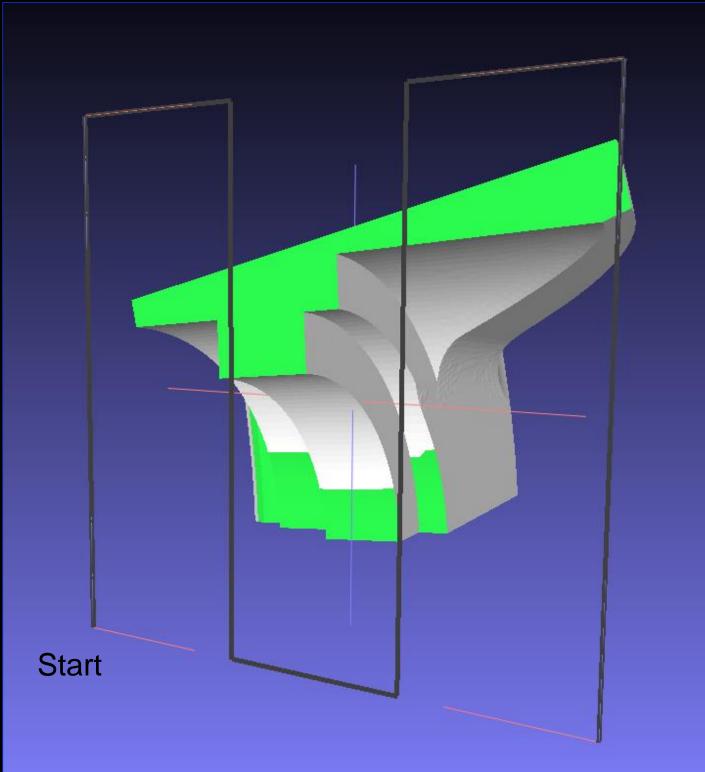


### Machine Vision for High Speed Printing





### Scanning – Path Planning



MeshLab

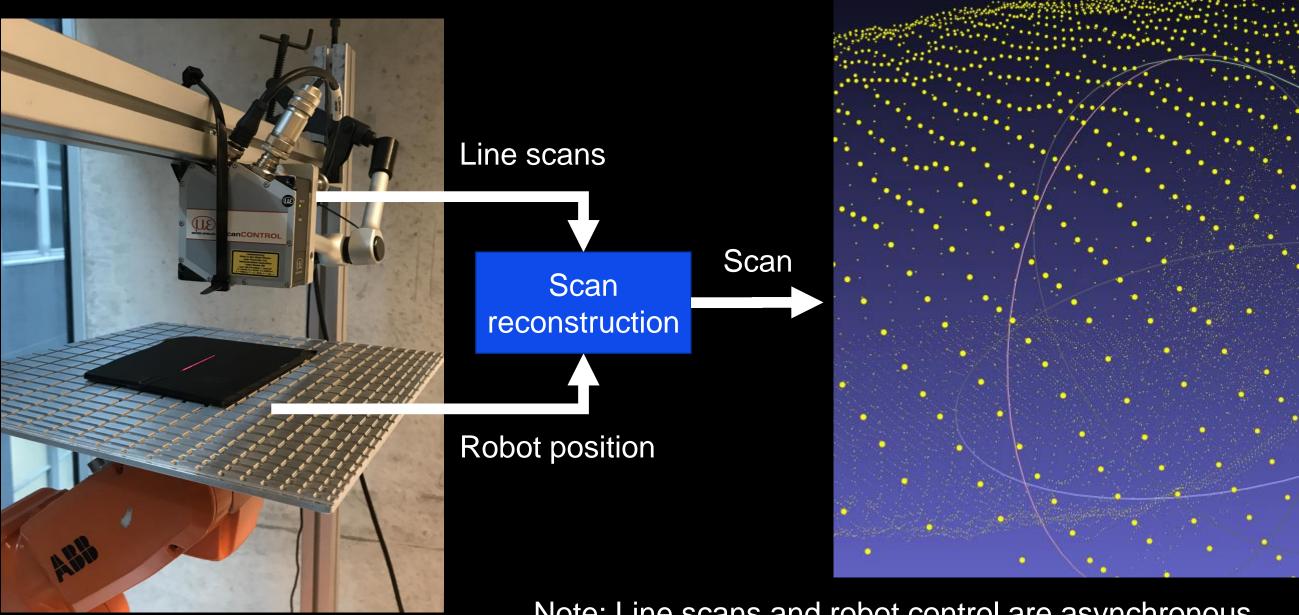




Guido Ranzuglia



### Scanning – Registering scan data to position



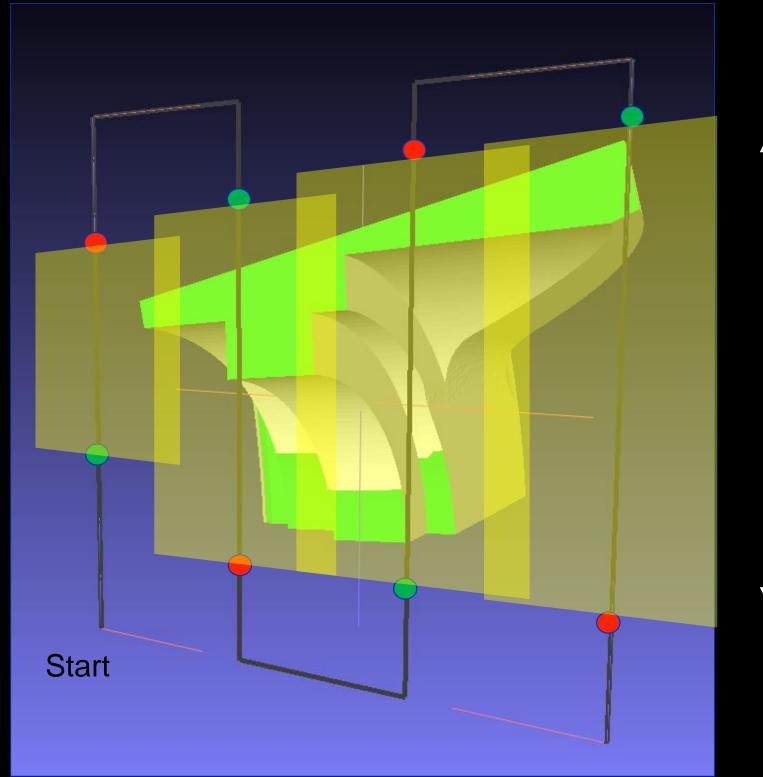
Note: Line scans and robot control are asynchronous. How to register line scans with robot position?

IMCrC





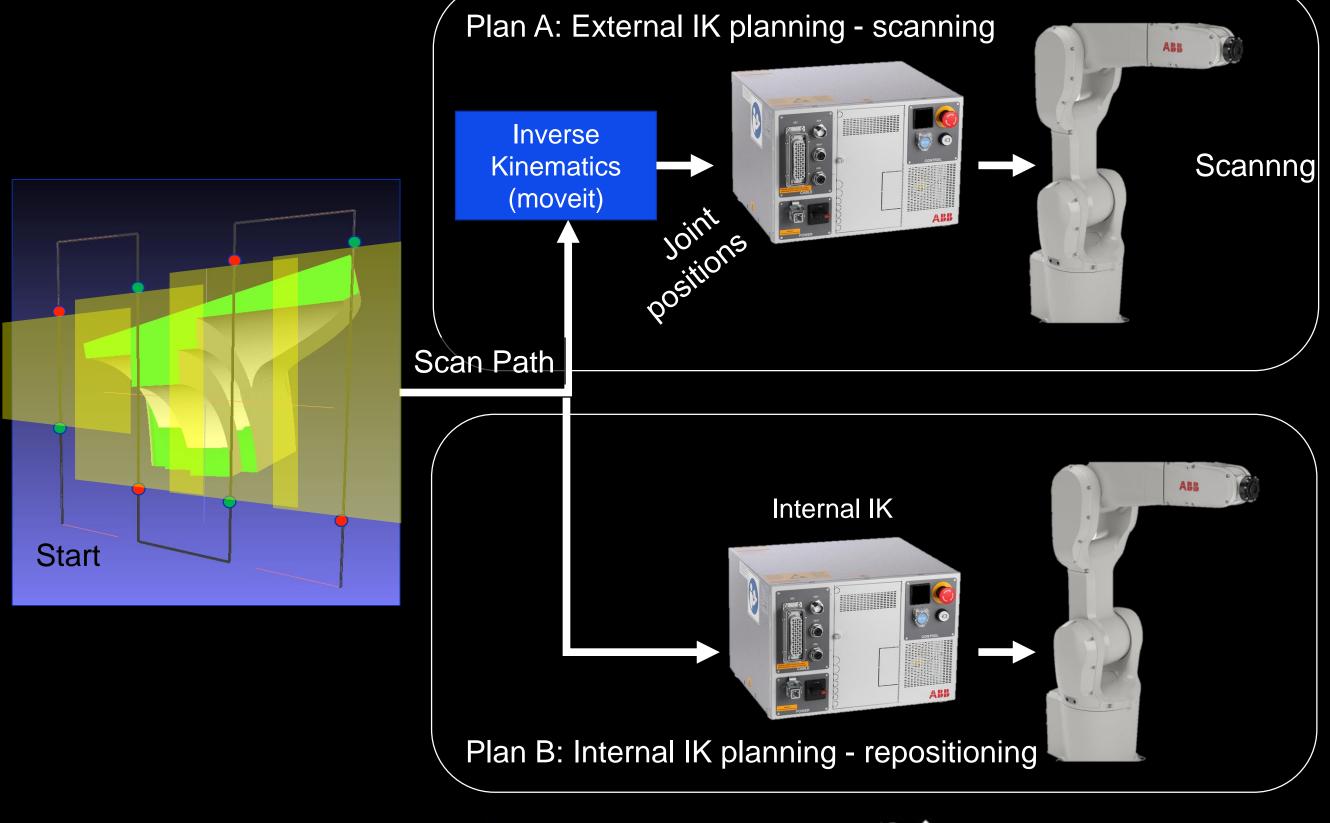
### Scanning – Motion Control



Constant velocity Constant orientation Linear motion



### Scanning – Motion Control Choices





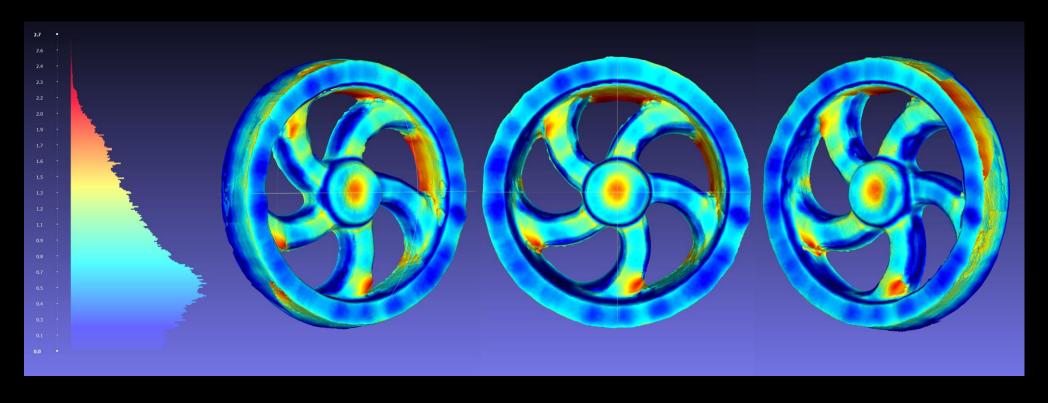


Rapido

#### **Project Results**

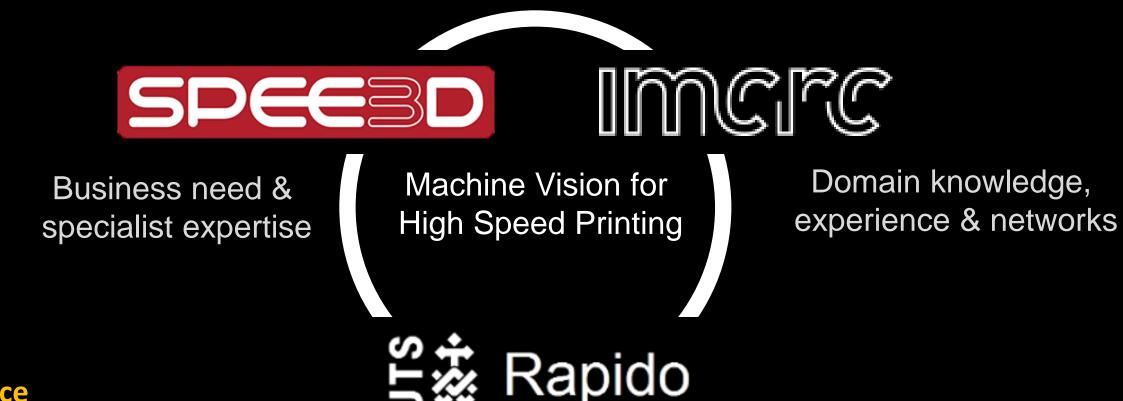
- Retrofit scanning solution
- Minimal additional components
- 300um median error with clear part identified







#### Collaborative Research - how it worked



#### ProtoSpace

900m2 UTS 3D Printing Precinct *Plastic, Metal, Electronic* 



#### **Industry focused R&D Expertise**

Hervé Harvard, Director Rapido & ProtoSpace Dr Mickey Clemon, 3D Printing & I4.0 Dr Don Bone, 3D Scanning

#### Bespoke 3D Printing Technology In Situ 3D Scanning - Spee3D & IMCRC 3D Printing & I4.0, mining - MT & IMCRC

FlexiFab, 3D Printing Open Platform

#### rapido@uts.edu.au

### NEW - Supersonic 3D Printing Design Challenge

- Open Industry and Research
- Best application using LightSPEE3D/WarpSPEE3D
- Submit CAD/drawing/description
- May 20<sup>th</sup> to June 30<sup>th</sup>
- Great prizes
- www.spee3d.com





#### ENTER TO WIN









## Thank you.

